CLAIMS

1. Signal processing method using a MAP (Maximum A Posteriori) type algorithm to determine a likelihood ratio $\Lambda_k^{\rm X}$ of a set of states X of a lattice at instant k, each of the said states being associated with at least one intermediate variable, belonging to the group including a so-called "forward" variable and a so-called "backward" variable, propagated by the said MAP algorithm and calculated recursively, in a direct direction and in an indirect direction respectively at the said instant k with respect to the said lattice,

characterised in that it includes a step for reducing the number of states selected by the said MAP type algorithm so as to calculate the said likelihood ratio,

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and in that for at least one determined value is assigned to the corresponding said forward and / or backward variable, so as to calculate an approximate likelihood ratio, at least for some non-selected states.

2. Method according to claim 1, characterised in that at a given instant K, the said at least one determined value a(k) assigned to the said forward variable is such that $0 \le a(k) \le \min_{i \in M_k'} (\alpha_i^k)$, and / or the said at least one determined value b(k) assigned to the said backward variable is such that $0 \le b(k) \le \min_{i \in M_k'} (\beta_i^k)$,

where M_k^f and M_k^b represent a set of the said states selected in the said direct direction and in the said

indirect direction respectively at the said instant k, and where α_i^k and β_i^k represent the said forward and backward variables respectively at the said instant k.

- 3. Method according to claim 2, characterised in that at a given instant k, the said determined value a(k) and / or b(k) is unique and is assigned to at least one forward variable α_i^k and / or backward variable β_i^k .
- 4. Method according to any of claims 1 to 3, characterised in that a constant value is assigned to the said forward and backward variables respectively, such that the said MAP type algorithm is a single-directional direct or indirect type algorithm respectively.

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- 5. Method according to any of claims 1 to 4, characterised in that the said step to reduce the number of states uses a "breadth-first" type lattice search algorithm.
- 6. Method according to claim 5, characterised in that the said "breadth-first" type algorithm is an M type algorithm.
- 7. Method according to claim 5, characterised in that the said "breadth-first" type algorithm is a T type algorithm using at least one threshold.
 - 8. Method according to claim 7, characterised in that the said at least one threshold is variable as a function of the said instant k.
 - 9. Method according to claim 8, characterised in that a predetermined value is assigned to the said variable threshold for each instant k.

- 10. Method according to claim 8, characterised in that for each instant k, the value of the said variable threshold is determined by the use of an adaptive algorithm.
- 11. Method according to claim 10, characterised in that the said adaptive algorithm is a gradient type algorithm.
 - 12. Method according to any of claims 10 and 11, characterised in that since the said lattice comprises a plurality of nodes each associated with one of the said states and at a given instant k, the value of the said variable threshold T at an instant (k+1) is determined by the following equation:

$$T(k+1) = T(k) - \mu(M(k) - M_c)$$

15 where T(k) represents the value of the said variable threshold at the said instant k,

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- $\ensuremath{\text{M}_{\text{c}}}$ is the target number of propagated nodes in the said lattice,
- M(k) is the number of propagated nodes in the said lattice at instant k,
 - and $\boldsymbol{\mu}$ is a positive constant representing a learning gain.
- 13. Method according to any of claims 11 and 12, characterised in that the said adaptive algorithm is a gradient type algorithm with variable pitch.
- 14. Method according to any of claims 12 and 13, characterised in that the said learning gain μ is a function of the said instant k.

15. Method according to any of claims 2 to 14, characterised in that since the said "breadth-first" type algorithm is an M type algorithm, the said determined values a(k) and / or b(k) assigned to the said "forward" and / or "backward" variables respectively, at a given instant k are given by the following equations:

$$a(k) = \min_{i \in M_k^f} (a_i^k) - C_f$$

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$$b(k) = \min_{i \in M_k^k} (\beta_i^k) - c_b$$

where c_f and c_b are two positive constants.

16. Method according to any of claims 2 to 14, characterised in that since the said "breadth-first" type algorithm is a T type algorithm, the said determined values a(k) and / or b(k) assigned to the said forward and / or backward variables at a given instant k respectively, are given by the following equations:

$$a(k) = T^f(k) - c_f$$

$$b(k) = T^b(k) - c_b$$

where c_f and c_b are two positive constants, and where $T^f(k)$ and $T^b(k)$ denote the value of the said variable threshold at said instant k in the said direct direction and in the said indirect direction respectively.

- 17. Method according to any of claims 1 to 16, characterised in that the said MAP type algorithm belongs to the group comprising:
- MAP type algorithms;
 - Log-MAP type algorithms;
 - Max-Log-MAP type algorithms.

- 18. Method according to any of claims 4 to 17, characterised in that since the said MAP type algorithm is a single-directional algorithm, the said method uses a step to compare decisions made by the said single-directional algorithm with the corresponding decisions made by a Viterbi type algorithm, called Viterbi decisions.
- 19. Method according to claim 18, characterised in that in the case of a negative comparison for at least one of the said decisions made by the said single-directional algorithm, the said method uses a substitution step for the said Viterbi decision corresponding to the said decision made by the said single-directional algorithm, called the substituted decision.

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- 20. Method according to claim 19, characterised in that a determined value V is assigned to the absolute value of the said likelihood ratio associated with the said substituted decision.
- 21. Method according to claim 20, characterised in that the said determined value V is equal to the absolute value of the average likelihood ratio of the sequence.
 - 22. Method according to claim 18, characterised in that in the case of a negative comparison for at least one of the said decisions made by the said single-directional algorithm, the said method uses a step for weighting the said likelihood ratio associated with the said decision considered, taking account of the said Viterbi decision.

- 23. Method according to claim 22, characterised in that when Y is a set of states associated with a decision D_i^Y output by the said Viterbi type algorithm at instant i, and Λ_i^Y represents the likelihood ratio associated with Y at instant i as calculated by the said single-directional algorithm during the said weighting step, the value of Λ_i^Y is replaced by $\widetilde{\Lambda}_i^Y$ defined by $\widetilde{\Lambda}_i^Y = \Lambda_i^Y + D_i^Y \times V$, where V is a determined value.
- 24. Method applicable, according to any of claims 1 to 23, to at least one of the domains belonging to the group comprising:
 - symbol detection;
 - signal coding / decoding;
 - turbo-decoding;
- turbo-detection;

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- source coding by quantification in lattice.
- 25. Communication signals receiver comprising means for implementing a MAP (Maximum A Posteriori) type algorithm to determine a likelihood ratio Λ_k^X of a set of states X of a lattice at instant k,
- each of the said states being associated with at least one intermediate variable belonging to the group comprising a so-called "forward" variable and a so-called "backward" variable propagated by the said MAP algorithm and calculated recursively in a direct direction and in an indirect direction respectively at the said instant k with respect to the said lattice,

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characterised in that it comprises means of reducing the number of states selected by the said MAP type algorithm in order to make a calculation of the said likelihood ratio,

5 and in that for at least some non-selected states, at least one determined value is assigned to the corresponding said forward variable and / or backward variable, so as to calculate an approximate likelihood ratio.